

MODULE - 1

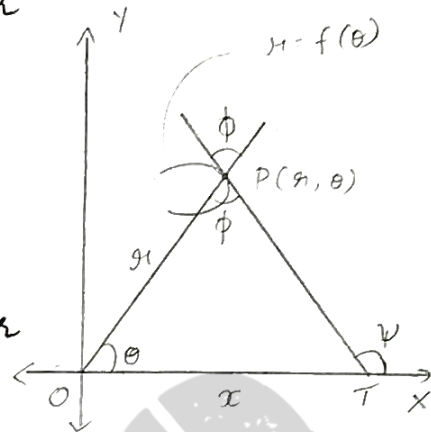
1) a) with usual notation prove that $\tan \phi = r \frac{d\theta}{dr}$

Let $P(r, \theta)$ be a point on the curve $r = f(\theta)$.

Hence $OP = r$ and $\angle xOP = \theta$

Let PT be the tangent to the curve $r = f(\theta)$ and let $\angle xTP = \psi$.

Let ϕ be the angle between the radius vector OP and the tangent PT i.e., $\angle OPT = \phi$



From the figure,

$$\psi = \phi + \theta$$

$$\tan \psi = \tan(\phi + \theta)$$

$$\tan \psi = \frac{\tan \phi + \tan \theta}{1 - \tan \phi \cdot \tan \theta} \quad \text{--- (1)}$$

If $P(x, y)$ are cartesian coordinates of P then we have,
 $x = r \cos \theta$, $y = r \sin \theta$

Also, WKT $\tan \psi = \frac{dy}{dx}$ = slope of the tangent

Divide both numerator and denominator by $d\theta$

$$\tan \psi = \frac{dy/d\theta}{dx/d\theta}$$

$$\tan \psi = \frac{\frac{d}{d\theta}(r \sin \theta)}{\frac{d}{d\theta}(r \cos \theta)}$$

$$\tan \psi = \frac{r \cdot \cos \theta + \sin \theta \frac{dr}{d\theta}}{-r \sin \theta + \cos \theta \frac{dr}{d\theta}}$$

$$\text{Let } \frac{dr}{d\theta} = r'$$

$$\tan \psi = \frac{r \cos \theta + r' \sin \theta}{r' \cos \theta - r \sin \theta}$$

Divide both numerator and denominator by $r' \cos \theta$

$$\tan \psi = \frac{\frac{r}{r'} + \tan \theta}{1 - \frac{r}{r'} \tan \theta} \quad \text{--- (2)}$$

Comparing ① and ②,

$$\tan \phi = \frac{r}{r'}$$

$$\Rightarrow \boxed{\tan \phi = r \frac{dr}{dr}}$$

1) b) Find the angle between the curves $r = a \log \theta$ and $r = \frac{a}{\log \theta}$

$$r = a \log \theta$$

take log on both sides

$$\log r = \log a + \log(\log \theta)$$

diff wrt θ

$$\frac{1}{r} \frac{dr}{d\theta} = 0 + \frac{1}{\log \theta} \left(\frac{1}{\theta} \right) (1)$$

$$\cot \phi_1 = \frac{1}{\theta \log \theta}$$

$$\boxed{\tan \phi_1 = \theta \log \theta}$$

$$r = \frac{a}{\log \theta}$$

take log on both sides

$$\log r = \log a - \log(\log \theta)$$

diff wrt θ

$$\frac{1}{r} \frac{dr}{d\theta} = 0 - \frac{1}{\log \theta} \left(\frac{1}{\theta} \right) (1)$$

$$\cot \phi_2 = \frac{-1}{\theta \log \theta}$$

$$\boxed{\tan \phi_2 = -\theta \log \theta}$$

$$\begin{aligned} \tan |\phi_1 - \phi_2| &= \frac{\tan \phi_1 - \tan \phi_2}{1 + \tan \phi_1 \cdot \tan \phi_2} \\ &= \frac{\theta \log \theta - (-\theta \log \theta)}{1 + \theta \log \theta (-\theta \log \theta)} \\ &= \frac{2\theta \log \theta}{1 - \theta^2 (\log \theta)^2} \end{aligned}$$

To find θ ,

consider $r = a \log \theta$; $r = \frac{a}{\log \theta}$

$$a \log \theta = \frac{a}{\log \theta}$$

$$(\log e)^2 = 1$$

$$\Rightarrow \boxed{\theta = e}$$

Substituting in eqⁿ ① we get,

$$\tan |\phi_1 - \phi_2| = \frac{2e \log e}{1 - e^2 (\log e)^2}$$

$$\text{but } \log e = 1$$

$$\tan |\phi_1 - \phi_2| = \frac{2e}{1 - e^2} \Rightarrow |\phi_1 - \phi_2| = \tan^{-1} \left(\frac{2e}{1 - e^2} \right)$$

1)c) Show that radius of curvature at any point θ on the cycloid $x = a(\theta + \sin \theta)$, $y = a(1 - \cos \theta)$ is $4a \cos^3 \left(\frac{\theta}{2} \right)$

$$x = a(\theta + \sin \theta)$$

$$y = a(1 - \cos \theta)$$

$$\frac{dx}{d\theta} = a + a \cos \theta$$

$$\frac{dy}{d\theta} = a(\sin \theta)$$

$$y_1 = \frac{dy}{dx} = \frac{dy/d\theta}{dx/d\theta}$$

$$y_1 = \frac{a \sin \theta}{a(1 + \cos \theta)}$$

$$y_1 = \frac{2 \sin \theta/2 \cos \theta/2}{2 \cos^2 \theta/2} \Rightarrow \boxed{y_1 = \tan \theta/2}$$

diff wrt x ,

$$y_2 = \sec^2 \left(\frac{\theta}{2} \right) \cdot \frac{d\theta}{dx} \cdot \frac{1}{2}$$

$$y_2 = \sec^2 \left(\frac{\theta}{2} \right) \cdot \frac{1}{2a(1 + \cos \theta)}$$

$$y_2 = \frac{1}{2a} \frac{\sec^2 \theta/2}{2 \cos^2 \theta/2} \Rightarrow$$

$$\boxed{y_2 = \frac{1}{4a} \sec^4 \left(\frac{\theta}{2} \right)}$$

$$r = \frac{(1 + y_1^2)^{3/2}}{y_2}$$

$$= \frac{(1 + \tan^2 \theta/2)^{3/2}}{\frac{1}{4a} \sec^4 \left(\frac{\theta}{2} \right)}$$

$$e = \frac{4a [\sec^2(\theta/2)]^{3/2}}{\sec^4(\frac{\theta}{2})}$$

$$e = \frac{4a}{\sec \theta/2} \Rightarrow \boxed{e = 4a \cos(\frac{\theta}{2})}$$

2)a) Show that the curves $r = a(1 + \sin \theta)$ and $r = a(1 - \sin \theta)$ cuts each other orthogonally.

$$r = a(1 + \sin \theta)$$

take log on both sides

$$\log r = \log a + \log(1 + \sin \theta)$$

diff wrt x ,

$$\frac{1}{r} \frac{dr}{d\theta} = 0 + \frac{1}{1 + \sin \theta} (\cos \theta)$$

$$\cot \phi_1 = \frac{\cos \theta}{1 + \sin \theta}$$

$$\cot \phi_1 \cdot \cot \phi_2 = \frac{\cos \theta}{1 + \sin \theta} \times \frac{-\cos \theta}{1 - \sin \theta}$$

$$= \frac{-\cos^2 \theta}{1^2 - \sin^2 \theta}$$

$$= \frac{-\cos^2 \theta}{\cancel{\cos^2 \theta}} \Rightarrow -1 //$$

$$r = a(1 - \sin \theta)$$

take log on both sides

$$\log r = \log a + \log(1 - \sin \theta)$$

diff wrt x ,

$$\frac{1}{r} \frac{dr}{d\theta} = 0 + \frac{1}{1 - \sin \theta} (-\cos \theta)$$

$$\cot \phi_2 = \frac{-\cos \theta}{1 - \sin \theta}$$

Since $\cot \phi_1 \cdot \cot \phi_2 = -1$ i.e., $|\phi_1 - \phi_2| = \pi/2$
 $\therefore$ The given two curves intersect orthogonally.

2)b) Find the pedal equation of curve $\frac{2a}{r} = (1 + \cos \theta)$

$$\log 2a - \log r = \log(1 + \cos \theta)$$

$$0 - \frac{1}{r} \frac{dr}{d\theta} = \frac{1}{1 + \cos \theta} (0 - \sin \theta)$$

$$\cot \phi = \frac{\sin \theta}{1 + \cos \theta}$$

pedal eqⁿ, $\frac{1}{p^2} = \frac{1}{r^2} [1 + \cot^2 \phi]$

$$\frac{1}{p^2} = \frac{1}{r^2} \left[1 + \frac{\sin^2 \theta}{(1 + \cos \theta)^2} \right]$$

$$\frac{1}{p^2} = \frac{1}{r^2} \left[\frac{1 + \cos^2 \theta + 2 \cos \theta + \sin^2 \theta}{(1 + \cos \theta)^2} \right]$$

$$\frac{1}{p^2} = \frac{1}{r^2} \left[\frac{2 + 2 \cos \theta}{(1 + \cos \theta)^2} \right]$$

$$\frac{1}{p^2} = \frac{2}{r^2} \left[\frac{1 + \cos \theta}{(1 + \cos \theta)^2} \right] \Rightarrow \boxed{\frac{1}{p^2} = \frac{2}{r^2} \left[\frac{1}{1 + \cos \theta} \right]}$$

To eliminate θ ,

$$1 + \cos \theta = \frac{2a}{r}$$

$$\Rightarrow \frac{1}{p^2} = \frac{2}{r^2} \times \frac{r}{2a} \Rightarrow \boxed{p = \sqrt{ar}}$$

2)c) Find the radius of curvature for curve $y^2 = \frac{4a^2(2a-x)}{x}$, where the curve meets x-axis.

$$y^2 = \frac{4a^2(2a-x)}{x}$$

$$xy^2 = 4a^2(2a-x)$$

Since the curve cuts the x-axis, we have $y=0$

Substitute $y=0$ in the given curve

$$xy^2 = 4a^2(2a-x)$$

$$x(0)^2 = 4a^2(2a-x)$$

$$4a^2x = 8a^3$$

$$x = \frac{8a^3}{4a^2} \Rightarrow \boxed{x = 2a}$$

Therefore, to find the ROC of given curve at $(2a, 0)$

Consider, $xy^2 = 4a^2(2a-x) \Rightarrow xy^2 = 8a^3 - 4a^2x$

Diff wrt to x

$$x \cdot 2yy_1 + y^2 \cdot 1 = 0 - 4a^2$$

$$2xyy_1 + y^2 = -4a^2$$

$$y_1 = \frac{-4a^2 - y^2}{2xy}$$

at $(2a, 0)$ $y_1 = \frac{-4a^2 - (0)^2}{2(2a)(0)}$

$$y_1 = \infty \text{ at } (2a, 0)$$

Since $y_1 = \infty$ at $(2a, 0)$ we consider,

$$x_1 = \frac{dx}{dy} = \frac{2xy}{-4a^2 - y^2}$$

at $(2a, 0)$ $x_1 = \frac{2(2a)(0)}{-4a^2 - 0} \Rightarrow x_1 = 0$

Consider, $x_1 = \frac{2xy}{-4a^2 - y^2} = \frac{2xy}{-(4a^2 + y^2)}$

$$(4a^2 + y^2)x_1 = -2xy$$

Diff wrt y

$$(4a^2 + y^2)x_2 + x_1(2y) = -2[x \cdot 1 + y \cdot x_1]$$

at $(2a, 0)$ $(4a^2 + 0^2)x_2 + 0 = -2[2a \cdot 1 + 0 \cdot x_1]$

$$4a^2 \cdot x_2 = -4a$$

$$x_2 = \frac{-4a}{4a^2} \Rightarrow \boxed{x_2 = -\frac{1}{a}}$$

ROC, $\rho = \frac{(1 + y_1^2)^{3/2}}{y_2}$

$$= \frac{[1 + 0]^{3/2}}{(-\frac{1}{a})} \Rightarrow \boxed{|\rho| = a}$$

MODULE-2

3)a) Show that, expand $\log(\sec x)$ upto term containing x^4 using Maclaurin's series.

→ Maclaurin's series expansion is given by:

$$y(x) = y(0) + xy_1(0) + \frac{x^2}{2!}y_2(0) + \dots \quad \text{--- (1)}$$

$$y(x) = \log(\sec x); \quad y(0) = \log(\sec 0) = \boxed{0}$$

$$y_1(x) = \frac{1}{\sec x} \cdot \sec x \cdot \tan x = \tan x; \quad y_1(0) = \tan 0 = \boxed{0}$$

$$y_2(x) = \sec^2 x; \quad y_2(0) = \sec^2(0) = \boxed{1}$$

$$y_2(x) = 1 + \tan^2 x$$

$$y_2(x) = 1 + y_1^2$$

$$y_3(x) = 2y_1y_2; \quad y_3(0) = 2(0)(1) = \boxed{0}$$

$$y_4(x) = 2\{y_1y_3 + y_2^2\}; \quad y_4(0) = 2\{0 + 1^2\} = \boxed{2}$$

Substitute in eqⁿ (1),

$$y(x) = \frac{x^2}{2!}(1) + \frac{x^2}{4!}(2)$$

$$y(x) = \frac{x^2}{2} + \frac{x^2}{24}(2) \Rightarrow \boxed{y(x) = \frac{x^2}{2} + \frac{x^2}{12}}$$

3)b) If $u = e^{ax+by} f(ax-by)$, prove that $b \frac{\partial u}{\partial x} + a \frac{\partial u}{\partial y} = 2abu$ by using the concept of composite functions.

→ $u = e^{ax+by} f(ax-by) \quad \text{--- (1)}$

Diff partially wrt to x

$$\frac{\partial u}{\partial x} = e^{ax+by} f'(ax-by) \frac{\partial}{\partial x} (ax-by) + f(ax-by) e^{ax+by} \frac{\partial}{\partial x} (ax+by)$$

$$\frac{\partial u}{\partial x} = e^{ax+by} f'(ax-by) \cdot a + f(ax-by) e^{ax+by} \cdot a$$

$$\frac{\partial u}{\partial x} = ae^{ax+by} f'(ax-by) + au$$

Multiply 'b' on both sides

$$b \cdot \frac{\partial u}{\partial x} = abe^{ax+by} f'(ax-by) + abu \quad \text{--- (2)}$$

Diff ① wrt y.

$$\frac{\partial u}{\partial y} = e^{ax+by} f'(ax-by)(-b) + f(ax-by) e^{ax+by} (b)$$

$$\frac{\partial u}{\partial y} = -be^{ax+by} f'(ax-by) + bu$$

Multiply 'a' on both sides

$$a \cdot \frac{\partial u}{\partial y} = -abe^{ax+by} f'(ax-by) + abu \quad \text{--- (3)}$$

Add eqⁿ ② and ③

$$\therefore \boxed{b \frac{\partial u}{\partial x} + a \frac{\partial u}{\partial y} = 2abu}$$

3) c) Find the extreme values of function $f(x, y) = x^3 + 3xy^2 - 3y^2 - 3x^2 + 4$

$$\rightarrow f(x, y) = x^3 + 3xy^2 - 3y^2 - 3x^2 + 4$$

$$f_x = 3x^2 + 3y^2 - 6x$$

$$f_y = 6xy - 6y$$

To find stationary points such that $f_x = 0$ and $f_y = 0$

$$3x^2 + 3y^2 - 6x = 0 \quad \text{--- (1)} \quad ; \quad 6xy - 6y = 0$$

$$(\div \text{ by } 6)$$

$$xy - y = 0$$

$$y(x-1) = 0$$

$$\boxed{y=0}$$

$$\boxed{x=1}$$

Substitute $y=0$ in eqⁿ ①,

$$3x^2 + 3y^2 - 6x = 0$$

$$(\div \text{ by } 3) \quad x^2 + y^2 - 2x = 0$$

$$x^2 - 2x = 0$$

$$x(x-2) = 0 \Rightarrow \boxed{x=0} \quad \boxed{x=2}$$

∴ Stationary points are $(0,0)$ $(2,0)$

Substitute $x=1$ in eqⁿ ①,

$$3x^2 + 3y^2 - 6x = 0$$

$$(\div 3) \quad x^2 + y^2 - 2x = 0$$

$$1 + y^2 - 2 = 0$$

$$y^2 - 1 = 0 \Rightarrow \boxed{y = \pm 1}$$

∴ Stationary points are $(1,-1)$ $(1,1)$

∴ Stationary points are $(0,0)$ $(2,0)$ $(1,-1)$ $(1,1)$

$$A = f_{xx} = 6x - 6$$

$$B = f_{xy} = 6y$$

$$C = f_{yy} = 6x - 6$$

	$(0,0)$	$(2,0)$	$(1,-1)$	$(1,1)$
$A = 6x - 6$	$-6 < 0$	$6 > 0$	0	0
$B = 6y$	0	0	-6	6
$C = 6x - 6$	-6	6	0	0
$AC - B^2$	$36 > 0$	$36 > 0$	-36	-36
Conclusion	Max point	Min point	Saddle point	Saddle point

$$\begin{aligned} \therefore \text{Minimum value of } f(2,0) &= x^3 + 3xy^2 - 3y^2 - 3x^2 + 4 \\ &= 2^3 + 2(2)(0) - 3(0) - 3(2)^2 + 4 \\ &= 8 + 0 - 0 - 12 + 4 \\ &= 0 \end{aligned}$$

$$\begin{aligned} \text{Maximum value of } f(0,0) &= 0 + 3(0)(0) - 3(0) - 3(0) + 4 \\ &= 4 \end{aligned}$$

4)a) Evaluate

$$(i) \quad \lim_{x \rightarrow 0} \left(\frac{a^x + b^x}{2} \right)^{\frac{1}{x}}$$

$$\rightarrow \text{Let } K = \lim_{x \rightarrow 0} \left(\frac{a^x + b^x}{2} \right)^{\frac{1}{x}}$$

$$\log_e K = \lim_{x \rightarrow 0} \frac{1}{x} \log \left(\frac{a^x + b^x}{2} \right)$$

$$\log_e K = \lim_{x \rightarrow 0} \frac{\log \left(\frac{a^x + b^x}{2} \right)}{x}$$

Apply LHR,

$$\log_e K = \lim_{x \rightarrow 0} \frac{1}{\left(\frac{a^x + b^x}{2} \right)} \cdot \frac{1}{2} \{ a^x \log a + b^x \log b \}$$

$$\log_e K = \lim_{x \rightarrow 0} \frac{1}{(a^x + b^x)} \{ a^x \log a + b^x \log b \}$$

$$\log_e K = \frac{1}{(a^0 + b^0)} \{ a^0 \log a + b^0 \log b \}$$

$$\log_e K = \frac{1}{2} \{ \log a + \log b \}$$

$$\log_e K = \frac{1}{2} (\log ab)$$

$$\log_e K = \log(ab)^{\frac{1}{2}}$$

$$K = (ab)^{\frac{1}{2}} \Rightarrow$$

$$K = \sqrt{ab}$$

$$(ii) \lim_{x \rightarrow 0} \left(\frac{\tan x}{x} \right)^{\frac{1}{x}}$$

$$\text{Let } K = \lim_{x \rightarrow 0} \left(\frac{\tan x}{x} \right)^{\frac{1}{x}}$$

$$\log_e K = \lim_{x \rightarrow 0} \frac{1}{x} \log \left(\frac{\tan x}{x} \right)$$

$$\log_e K = \lim_{x \rightarrow 0} \frac{\log \left(\frac{\tan x}{x} \right)}{x}$$

Apply LHR,

$$\log_e K = \lim_{x \rightarrow 0} \frac{1}{\left(\frac{\tan x}{x}\right)} \left\{ \frac{x \cdot \sec^2 x - \tan x \cdot 1}{x^2} \right\}$$

$$\log_e K = \lim_{x \rightarrow 0} \frac{x \cdot \sec^2 x - \tan x}{x^2} \quad \left(\because \lim_{x \rightarrow 0} \frac{\tan x}{x} = 1 \right)$$

Apply LHR,

$$\log_e K = \lim_{x \rightarrow 0} \frac{x \cdot 2 \sec^2 x \cdot \tan x + \sec^2 x \cdot 1 - \sec^2 x}{2x}$$

$$\log_e K = \lim_{x \rightarrow 0} \frac{2x \sec^2 x \cdot \tan x}{2x}$$

$$\log_e K = \lim_{x \rightarrow 0} \frac{\sec^2 x \cdot \tan x}{1}$$

$$\log_e K = \frac{\sec^2(0) \cdot \tan(0)}{1}$$

$$\log_e K = 0 \Rightarrow \boxed{K = e^0 = 1}$$

b) If $u = f(x-y, y-z, z-x)$ show that $\frac{\partial u}{\partial x} + \frac{\partial u}{\partial y} + \frac{\partial u}{\partial z} = 0$

Let $p = x-y$, $q = y-z$, $r = z-x$

$\therefore u \rightarrow (p, q, r) \rightarrow (x, y, z) \Rightarrow u \rightarrow (x, y, z)$

$\frac{\partial u}{\partial x}$, $\frac{\partial u}{\partial y}$, $\frac{\partial u}{\partial z}$ exists

$$\frac{\partial u}{\partial x} = u_x = \frac{\partial u}{\partial p} \cdot \frac{\partial p}{\partial x} + \frac{\partial u}{\partial q} \frac{\partial q}{\partial x} + \frac{\partial u}{\partial r} \cdot \frac{\partial r}{\partial x}$$

$$\frac{\partial u}{\partial x} = \frac{\partial u}{\partial p} (1) + \frac{\partial u}{\partial q} (0) + \frac{\partial u}{\partial r} (-1)$$

$$\boxed{\frac{\partial u}{\partial x} = \frac{\partial u}{\partial p} - \frac{\partial u}{\partial r}} \quad \text{--- ①}$$

$$\frac{\partial u}{\partial y} = \frac{\partial u}{\partial p} \cdot \frac{\partial p}{\partial y} + \frac{\partial u}{\partial q} \cdot \frac{\partial q}{\partial y} + \frac{\partial u}{\partial r} \cdot \frac{\partial r}{\partial y}$$

$$\frac{\partial u}{\partial y} = \frac{\partial u}{\partial p} (-1) + \frac{\partial u}{\partial q} (1) + \frac{\partial u}{\partial r} (0)$$

$$\boxed{\frac{\partial u}{\partial y} = -\frac{\partial u}{\partial p} + \frac{\partial u}{\partial q}} \quad \text{--- (2)}$$

$$\frac{\partial u}{\partial z} = \frac{\partial u}{\partial p} \cdot \frac{\partial p}{\partial z} + \frac{\partial u}{\partial q} \cdot \frac{\partial q}{\partial z} + \frac{\partial u}{\partial r} \cdot \frac{\partial r}{\partial z}$$

$$\frac{\partial u}{\partial z} = \frac{\partial u}{\partial p} (0) + \frac{\partial u}{\partial q} (-1) + \frac{\partial u}{\partial r} (1)$$

$$\boxed{\frac{\partial u}{\partial z} = -\frac{\partial u}{\partial q} + \frac{\partial u}{\partial r}} \quad \text{--- (3)}$$

Add (1), (2) and (3)

$$\frac{\partial u}{\partial x} + \frac{\partial u}{\partial y} + \frac{\partial u}{\partial z} = \frac{\partial u}{\partial p} - \frac{\partial u}{\partial r} - \frac{\partial u}{\partial p} + \frac{\partial u}{\partial q} - \frac{\partial u}{\partial q} + \frac{\partial u}{\partial r}$$

$$\therefore \boxed{\frac{\partial u}{\partial x} + \frac{\partial u}{\partial y} + \frac{\partial u}{\partial z} = 0}$$

4) If $x+y+z=u$, $y+z=v$ and $z=uvw$ find values of $\frac{\partial(x,y,z)}{\partial(u,v,w)}$

$$J \left(\frac{x,y,z}{u,v,w} \right) = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} & \frac{\partial x}{\partial w} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} & \frac{\partial y}{\partial w} \\ \frac{\partial z}{\partial u} & \frac{\partial z}{\partial v} & \frac{\partial z}{\partial w} \end{vmatrix}$$

consider, $x+y+z=u$

$$x+v=u$$

$$x=v-u$$

$$y+z=v$$

$$y=v-z$$

$$y = v - uvw$$

$$z=uvw$$

$$\frac{\partial x}{\partial u} = 1 - 0 = 1$$

$$\frac{\partial y}{\partial u} = 0 - v\omega = -v\omega$$

$$\frac{\partial z}{\partial u} = v\omega$$

$$\frac{\partial x}{\partial v} = -1$$

$$\frac{\partial y}{\partial v} = 1 - u\omega = 1 - u\omega$$

$$\frac{\partial z}{\partial v} = u\omega$$

$$\frac{\partial x}{\partial \omega} = 0$$

$$\frac{\partial y}{\partial \omega} = -uv$$

$$\frac{\partial z}{\partial \omega} = uv$$

$$J\left(\frac{u, v, \omega}{x, y, z}\right) = \begin{vmatrix} 1 & -1 & 0 \\ -v\omega & 1 - u\omega & -uv \\ v\omega & u\omega & uv \end{vmatrix}$$

$$J = 1[uv - u^2v\omega - [-u^2v\omega]] + 1[-uv/\omega + u/\omega^2\omega] + 0$$

$$J = 1[uv - u^2v\omega + u^2v\omega] + 1[0]$$

$$J = uv$$

5) a) solve $\frac{dy}{dx} + \frac{y}{x} = x^2 y^6$

→ $\frac{dy}{dx} + \frac{y}{x} = x^2 y^6$ ——— (1)

given DE is of the form $\frac{dy}{dx} + Py = Qy^n$

eqn (1) divide y^6 throughout,

$$\frac{1}{y^6} \frac{dy}{dx} + \frac{1}{x} \cdot \frac{1}{y^5} = x^2 \text{ ——— (2)}$$

Substitute $\frac{1}{y^5} = t$

diff wrt to x

$$-\frac{5}{y^6} \cdot \frac{dy}{dx} = \frac{dt}{dx} \Rightarrow \frac{1}{y^6} \frac{dy}{dx} = -\frac{1}{5} \cdot \frac{dt}{dx}$$

Substitute in (1), $-\frac{1}{5} \frac{dt}{dx} + \frac{1}{x} \cdot t = x^2$

(x^4 by -5) $\frac{dt}{dx} - 5 \cdot \frac{1}{x} \cdot t = -5x^2$ ——— (3)

$$\frac{dt}{dx} + Pt = Q; \text{ where } P = -5 \cdot \frac{1}{x}; Q = -5x^2$$

$$\text{IF} = e^{\int P \cdot dx} = e^{-5 \int \frac{1}{x} dx} = e^{(\log x)^{-5}} = x^{-5} = \frac{1}{x^5}$$

soln of (3) is given by -

$$t(\text{IF}) = \int Q(\text{IF}) dx + c$$

$$t \cdot \frac{1}{x^5} = \int -5x^2 \cdot \frac{1}{x^5} \cdot dx + c$$

$$t \cdot \frac{1}{x^5} = -5 \int \frac{1}{x^3} \cdot dx + c$$

$$t \cdot \frac{1}{x^5} = -5 \frac{x^{-2}}{-2} + c$$

$$\boxed{\frac{1}{y^5} \cdot \frac{1}{x^5} = \frac{5}{2} x^{-2} + c}$$

b) Find orthogonal trajectories of $\frac{x^2}{a^2} + \frac{y^2}{b^2 + \lambda} = 1$, where λ is a parameter

$$\frac{x^2}{a^2} + \frac{y^2}{b^2 + \lambda} = 1 \quad \text{--- (1)}$$

$$\frac{x^2(b^2 + \lambda) + a^2 y^2}{a^2(b^2 + \lambda)} = 1$$

$$x^2(b^2 + \lambda) + a^2 y^2 = a^2(b^2 + \lambda)$$

diff wrt x

$$2x(b^2 + \lambda) + a^2 \cdot 2y \frac{dy}{dx} = 0$$

$$(\div 2) \quad x(b^2 + \lambda) + a^2 y \frac{dy}{dx} = 0$$

$$(b^2 + \lambda)x = -a^2 y \frac{dy}{dx}$$

$$(b^2 + \lambda) = -\frac{a^2 y}{x} \frac{dy}{dx}$$

Substitute in equation (1),

$$\frac{x^2}{a^2} + \frac{y^2}{-\frac{a^2 y}{x} \frac{dy}{dx}} = 1$$

$$\frac{x^2}{a^2} - \frac{xy}{a^2} \cdot \frac{dx}{dy} = 1$$

Replace $-\frac{dx}{dy}$ by $\frac{dy}{dx}$

$$\Rightarrow \frac{x^2}{a^2} + \frac{xy}{a^2} \cdot \frac{dy}{dx} = 1$$

$$x^2 + xy \cdot \frac{dy}{dx} = a^2$$

$$xy \cdot \frac{dy}{dx} = a^2 - x^2$$

$$y \cdot dy = \left(\frac{a^2 - x^2}{x} \right) dx$$

$$\int y \cdot dy = \int \frac{a^2}{x} \cdot dx - \int x \cdot dx + C$$

$$\frac{y^2}{2} = a^2 \log x - \frac{x^2}{2} + C$$

$$\boxed{y^2 = 2a^2 \log x - x^2 + 2C}$$

c) solve $xyp^2 - (x^2 + y^2)p + xy = 0$

$$xyp^2 + xy = (x^2 + y^2)p$$

$$xyp^2 - (x^2 + y^2)p + xy = 0$$

It is similar to $ax^2 + bx + c = 0$

$$x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

Here $a = xy$, $b = -(x^2 + y^2)$, $c = xy$

$$p = \frac{(x^2 + y^2) \pm \sqrt{(x^2 + y^2)^2 - 4(xy)(xy)}}{2xy}$$

$$= \frac{(x^2 + y^2) \pm \sqrt{x^2 + y^2 + 2x^2y^2 - 4x^2y^2}}{2xy}$$

$$= \frac{(x^2 + y^2) \pm \sqrt{(x^2 - y^2)^2}}{2xy}$$

$$= \frac{(x^2 + y^2) \pm (x^2 - y^2)}{2xy}$$

$$p = \frac{(x^2 + y^2) + (x^2 - y^2)}{2xy}$$

$$p = \frac{2x^2}{2xy} = \frac{x}{y}$$

$$p = \frac{(x^2 + y^2) - (x^2 - y^2)}{2xy}$$

$$p = \frac{2y^2}{2xy} = \frac{y}{x}$$

$$\frac{dy}{dx} = \frac{x}{y}$$

$$y \cdot dy = x \cdot dx$$

$$\int y \cdot dy = \int x \cdot dx$$

$$\frac{y^2}{2} = \frac{x^2}{2} + c$$

$$\frac{y^2}{2} \pm \frac{x^2 + 2c}{2}$$

$$y^2 - x^2 - k = 0$$

$$\frac{dy}{dx} = \frac{y}{x}$$

$$\frac{1}{y} \cdot dy = \frac{1}{x} \cdot dx$$

$$\int \frac{1}{y} \cdot dy = \int \frac{1}{x} \cdot dx$$

$$\log y = \log x + c$$

$$\log y = \log x + \log k$$

$$\log y = \log (xk)$$

$$y = xk \Rightarrow y - xk = 0$$

General solution is $(y^2 - x^2 - k)(y - xk) = 0$

Qa) solve $(x^2 + y^2 + x)dx + xy \cdot dy = 0$

$$(x^2 + y^2 + x)dx + xy \cdot dy = 0 \quad \text{--- (1)}$$

$$M = x^2 + y^2 + x$$

$$N = xy$$

$$\frac{\partial M}{\partial y} = 2y$$

$$\frac{\partial N}{\partial x} = y$$

$$\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x} \Rightarrow \text{equation (1) is not exact}$$

$$\frac{\partial M}{\partial y} - \frac{\partial N}{\partial x} = 2y - y = y \quad \text{--- close to } N$$

$$\frac{\frac{\partial M}{\partial y} - \frac{\partial N}{\partial x}}{N} = \frac{y}{xy} = \frac{1}{x} = f(x)$$

$$\therefore IF = e^{\int f(x) \cdot dx} = e^{\int \frac{1}{x} \cdot dx} = e^{\log x} \Rightarrow \boxed{IF = x}$$

Multiply IF to equation (1),

$$(x^3 + xy^2 + x^2)dx + x^2y \cdot dy = 0 \quad \text{--- (2)}$$

$$\frac{\partial M}{\partial y} = 2xy$$

$$\frac{\partial N}{\partial x} = 2xy$$

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x} \Rightarrow \text{eqn (2) is exact}$$

solⁿ to eqn ① is -

$$\int M dx + \int (N \text{ terms free from } x) dy = C$$

y-const

$$\int (x^3 + xy^2 + x^2) dx + \int 0 \cdot dy = C$$

y-const

$$\Rightarrow \boxed{\frac{x^4}{4} + \frac{x^2 y^2}{2} + \frac{x^3}{3} = C}$$

- c) Find general solution of equation $(px-y)(py+x) = a^2 p$ by reducing into Clairaut's form by taking the substitution $x = x^2, y = y^2$?

$$(px-y)(py+x) = a^2 p \quad \text{--- ①}$$

given:

$$x = x^2$$

$$y = y^2$$

$$\frac{dx}{dx} = 2x$$

$$\frac{dy}{dy} = 2y$$

wkt,

$$p = \frac{dy}{dx}$$

$$p = \frac{dy}{dy} \cdot \frac{dy}{dx} \cdot \frac{dx}{dx}$$

$$p = \frac{1}{2y} \cdot p \cdot 2x$$

$$\boxed{p = \frac{\sqrt{x}}{\sqrt{y}} p}$$

Substitute in ①,

$$\left[\frac{\sqrt{x} \cdot P \cdot \sqrt{x} - \sqrt{y}}{\sqrt{y}} \right] \left[\frac{\sqrt{x} \cdot P \cdot \sqrt{y} + \sqrt{x}}{\sqrt{y}} \right] = a^2 \frac{\sqrt{x}}{\sqrt{y}} \cdot P^2$$

$$\left[\frac{XP - Y}{\sqrt{Y}} \right] [\sqrt{X}P + \sqrt{X}] = \frac{a^2 \sqrt{X}}{\sqrt{Y}} P$$

$$(PX - Y) [\sqrt{X} (P+1)] = a^2 \sqrt{X} P$$

$$PX - Y = \frac{a^2 P}{P+1}$$

$$Y = PX - \frac{a^2 P}{P+1}$$

This is in Clairaut's form

Replace P by C

General solution is : $Y = CX - \frac{a^2 C}{C+1}$

$$\Rightarrow \boxed{y^2 = cx^2 - \frac{a^2 c}{c+1}}$$

- b) A series circuit with resistance R, inductance L and electromotive force ~~F~~ is governed by D.E

$L \frac{di}{dt} + Ri = E$ where L and R are constants and initially current i is zero. Find the current at time t?

$$\rightarrow L \frac{di}{dt} + Ri = E$$

($\div$ by L throughout)

$$\frac{di}{dt} + \frac{Ri}{L} = \frac{E}{L}$$

This is a linear D.E in i of form $\frac{dy}{dx} + Py = Q$

Here, $P = \frac{R}{L}$, $Q = \frac{E}{L}$

$$IF = e^{\int P \cdot dt} = e^{\int \frac{R}{L} dt} = e^{\frac{R}{L} \cdot t}$$

Solution: $y(IF) = \int Q(IF) dt + C$

$$i(IF) = \int Q(IF) dt + C$$

$$i \cdot e^{\frac{Rt}{L}} = \int \frac{E}{L} \cdot e^{\frac{Rt}{L}} dt + C$$

$$i \cdot e^{\frac{Rt}{L}} = \frac{E}{\cancel{L}} \cdot \frac{e^{\frac{Rt}{L}}}{\cancel{\frac{R}{L}}} + C_1$$

$$i \cdot e^{\frac{Rt}{L}} = \frac{E}{R} \cdot e^{\frac{Rt}{L}} + C_1$$

$$(\div \text{ by } e^{\frac{Rt}{L}})$$

$$i = \frac{E}{R} + C_1 e^{-\frac{Rt}{L}} \quad \text{--- (1)}$$

Eqⁿ ① is the general solution of given DE given:- Initially current is 0

i.e., $i = 0$ when $t = 0$

$$0 = \frac{E}{R} + C_1 e^0 \Rightarrow \boxed{C_1 = -\frac{E}{R}}$$

Substitute C_1 in eqⁿ ①,

$$i = \frac{E}{R} - \frac{E}{R} \cdot e^{-\frac{Rt}{L}}$$

$$\boxed{i = \frac{E}{R} \left(1 - e^{-\frac{Rt}{L}} \right)}$$

MODULE - 4

7a) Find the least positive values of x such that

(i) $71 \equiv x \pmod{8}$

(ii) $78+x \equiv 3 \pmod{5}$

(iii) $89 \equiv (x+3) \pmod{4}$

→ (i) $71 \equiv x \pmod{8}$

$x=7$ is the least positive value

(ii) $78+x \equiv 3 \pmod{5}$

$$78+x-3 \equiv 0 \pmod{5}$$

$$75+x \equiv 5 \times K$$

By inspection,

$x=5$ is the least positive value because $75+5=80=5 \times \underline{16}$

(iii) $89 \equiv (x+3) \pmod{4}$

$$86-x \equiv 0 \pmod{4}$$

$$86-x \equiv 4K$$

By inspection,

$x=2$ is the least positive value because $86-2=84=4 \times \underline{21}$

7b) Find the remainder when $(\overset{349}{344} \times 74 \times 36)$ is divided by 3

→ $349 \equiv 1 \pmod{3}$

$$74 \equiv 2 \pmod{3}$$

$$36 \equiv 0 \pmod{3}$$

$$\begin{aligned}\therefore (349 \times 74 \times 36) &\equiv (1 \times 2 \times 0) \pmod{3} \\ &\equiv 0 \pmod{3}\end{aligned}$$

$\therefore 0$ is the remainder when $349 \times 74 \times 36$ is divided by 3

7)c) solve $2x + 6y \equiv 1 \pmod{7}$
 $4x + 3y \equiv 2 \pmod{7}$

→ Here, $a = 2$, $b = 6$, $x = 1$
 $c = 4$, $d = 3$, $s = 2$; $n = 7$

$$\gcd(a, b, n) = \gcd(2, 6, 7) = 1 \text{ and } 1/4$$

$\therefore$ system has solution.

$$\gcd(ad - bc, n) = \gcd(18, 7) = 1$$

$\therefore$ The system has unique solution

consider, $2x + 6y \equiv 1 \pmod{7} \quad (\times 2)$
 $4x + 3y \equiv 2 \pmod{7}$

$$4x + 12y \equiv 2 \pmod{7}$$

$$4x + 3y \equiv 2 \pmod{7}$$

$$9y \equiv 0 \pmod{7}$$

By inspection, $y = 0$

$\therefore y \equiv 0 \pmod{7}$

consider $2x + 6y \equiv 1 \pmod{7}$

$$2x \equiv 1 \pmod{7} \quad (\because y=0)$$

By inspection,

$x=4$ satisfies the equation

$$\therefore x \equiv 4 \pmod{7}$$

Thus solution is $x \equiv 4 \pmod{7}$; $y \equiv 0 \pmod{7}$

8)a) (i) Find the last digit of 7^{2013}

(ii) Find the last digit of 13^{37}

$$\begin{aligned} \rightarrow (i) \quad 7^{2013} &= 7^{4 \times 503 + 1} \\ &= 7^{4K+1} \\ &\equiv 7 \pmod{10} \end{aligned}$$

$$\begin{array}{r} 4 \overline{) 2013} \quad (503) \\ \underline{20} \\ 013 \\ \underline{12} \\ 1 \end{array}$$

$\therefore 7$ is the last digit

$$(ii) \quad 13 \equiv 13 \pmod{10}$$

$$13^2 \equiv 13^2 \pmod{10}$$

$$13^2 \equiv 169 \pmod{10}$$

$$13^2 \equiv 9 \pmod{10}$$

$$13^2 \equiv -1 \pmod{10}$$

$$(13^2)^8 \equiv (-1)^8 \pmod{10}$$

$$13^{36} \equiv 1 \pmod{10}$$

$$13^{36} \cdot 13^1 \equiv 13 \pmod{10}$$

$$13^{37} \equiv 3 \pmod{10}$$

$\therefore$ Unit digit = 3

8)b) Find the remainder when number 2^{1000} is divided by 13

→ $a = 2, p = 13$

$$\gcd(2, 13) = 1$$

By Fermat's little theorem,

$$a^{p-1} \equiv 1 \pmod{p}$$

$$2^{12} \equiv 1 \pmod{13}$$

$$(2^{12})^{83} \equiv 1^{83} \pmod{13}$$

$$2^{996} \equiv 1 \pmod{13}$$

$$2^{996} \cdot 2^4 \equiv 16 \pmod{13}$$

$$2^{1000} \equiv 16 \pmod{13}$$

$$2^{1000} \equiv 3 \pmod{13}$$

$$\begin{array}{r} 12 \overline{) 1000} 83 \\ \underline{96} \\ 40 \\ \underline{36} \\ 4 \end{array}$$

$$\begin{array}{r} 13 \overline{) 16} 1 \\ \underline{13} \\ 3 \end{array}$$

∴ 3 is the remainder when 2^{1000} is divided by 13.

8)c) Find the remainder when $14!$ is divided by 17

→ Here, $p = 17$

By Wilson's theorem,

$$(p-1)! \equiv -1 \pmod{p}$$

$$16! \equiv -1 \pmod{17}$$

$$16 \times 15 \times 14! \equiv -1 \pmod{17}$$

$$(-1) \times (-2) \times 14! \equiv -1 \pmod{17}$$

$$2 \times 14! \equiv 16 \pmod{17}$$

$$(\div 2) \Rightarrow 14! \equiv 8 \pmod{17} \Rightarrow 8 \text{ is the remainder.}$$

MODULE - 5

9) a) Find rank of matrix $\begin{bmatrix} 2 & -1 & -3 & -1 \\ 1 & 2 & 3 & -1 \\ 1 & 0 & 1 & 1 \\ 0 & 1 & 1 & -1 \end{bmatrix}$

$$A = \begin{bmatrix} 2 & -1 & -3 & -1 \\ 1 & 2 & 3 & -1 \\ 1 & 0 & 1 & 1 \\ 0 & 1 & 1 & -1 \end{bmatrix}$$

$$R_2 \rightarrow 2R_2 - R_1; \quad R_3 \rightarrow 2R_3 - R_1$$

$$A = \begin{bmatrix} 2 & -1 & -3 & -1 \\ 0 & 5 & 9 & -1 \\ 0 & 1 & 5 & 3 \\ 0 & 1 & 1 & -1 \end{bmatrix}$$

$$R_3 \rightarrow 5R_3 - R_2; \quad R_4 \rightarrow 5R_4 - R_2$$

$$A \sim \begin{bmatrix} 2 & -1 & -3 & -1 \\ 0 & 5 & 9 & -1 \\ 0 & 0 & 16 & 16 \\ 0 & 0 & -4 & -4 \end{bmatrix}$$

$$R_4 \rightarrow 4R_4 + R_3$$

$$A \sim \begin{bmatrix} 2 & -1 & -3 & -1 \\ 0 & 5 & 9 & -1 \\ 0 & 0 & 16 & 16 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$R_1 \rightarrow \frac{1}{2}R_1; \quad R_2 \rightarrow \frac{1}{5}R_2; \quad R_3 \rightarrow \frac{1}{16}R_3$$

$$A \sim \begin{bmatrix} 1 & -\frac{1}{2} & -\frac{3}{2} & -\frac{1}{2} \\ 0 & 1 & \frac{9}{5} & -\frac{1}{5} \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\therefore \boxed{\rho(A) = 3}$$

9) b) Solve system of equation using gauss-Jordan method
 $x + y + z = 10; \quad 2x - y + 3z = 19; \quad x + 2y + 3z = 22$

consider the augmented matrix

$$[A:B] = \left[\begin{array}{ccc|c} 1 & 1 & 1 & 10 \\ 2 & -1 & 3 & 19 \\ 1 & 2 & 3 & 22 \end{array} \right]$$

$$R_2 \rightarrow R_2 - 2R_1 ; R_3 \rightarrow R_3 - R_1$$

$$[A:B] \sim \left[\begin{array}{ccc|c} 1 & 1 & 1 & 10 \\ 0 & -3 & 1 & -1 \\ 0 & 1 & 2 & 12 \end{array} \right]$$

$$R_1 \rightarrow 3R_1 + R_2 ; R_3 \rightarrow 3R_3 + R_2$$

$$[A:B] \sim \left[\begin{array}{ccc|c} 3 & 0 & 4 & 29 \\ 0 & -3 & 1 & -1 \\ 0 & 0 & 7 & 35 \end{array} \right]$$

$$R_1 \rightarrow 7R_1 - 4R_3 ; R_2 \rightarrow 7R_2 - R_3$$

$$[A:B] \sim \left[\begin{array}{ccc|c} 21 & 0 & 0 & 63 \\ 0 & -21 & 0 & -42 \\ 0 & 0 & 7 & 35 \end{array} \right]$$

System of equation are:

$$\begin{aligned} 21x - 63 & ; -21y = -42 & ; 7z = 35 \\ \Rightarrow \boxed{x=3} & \Rightarrow \boxed{y=2} & \Rightarrow \boxed{z=5} \end{aligned}$$

$x=3, y=2, z=5$ is the solution

9c) Using power method find largest eigen value and corresponding eigen vector of matrix $A = \begin{bmatrix} 2 & 0 & 1 \\ 0 & 2 & 0 \\ 1 & 0 & 2 \end{bmatrix}$

$$AX^{(0)} = \begin{bmatrix} 2 & 0 & 1 \\ 0 & 2 & 0 \\ 1 & 0 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix} = 2 \begin{bmatrix} 1 \\ 0 \\ 0.5 \end{bmatrix} = \lambda^{(1)} x^{(1)}$$

$$AX^{(1)} = \begin{bmatrix} 2 & 0 & 1 \\ 0 & 2 & 0 \\ 1 & 0 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 0.5 \end{bmatrix} = \begin{bmatrix} 2.5 \\ 0 \\ 2 \end{bmatrix} = 2.5 \begin{bmatrix} 1 \\ 0 \\ 0.8 \end{bmatrix} = \lambda^{(2)} x^{(2)}$$

$$AX^{(2)} = \begin{bmatrix} 2 & 0 & 1 \\ 0 & 2 & 0 \\ 1 & 0 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 0.8 \end{bmatrix} = \begin{bmatrix} 2.8 \\ 0 \\ 2.6 \end{bmatrix} = 2.8 \begin{bmatrix} 1 \\ 0 \\ 0.929 \end{bmatrix} = \lambda^{(3)} x^{(3)}$$

$$AX^{(3)}: \begin{bmatrix} 2 & 0 & 1 \\ 0 & 2 & 0 \\ 1 & 0 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 0.929 \end{bmatrix} = \begin{bmatrix} 2.929 \\ 0 \\ 2.858 \end{bmatrix} = 2.929 \begin{bmatrix} 1 \\ 0 \\ 0.976 \end{bmatrix} = \lambda^{(4)} x^{(4)}$$

$$AX^{(4)}: \begin{bmatrix} 2 & 0 & 1 \\ 0 & 2 & 0 \\ 1 & 0 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 0.976 \end{bmatrix} = \begin{bmatrix} 2.976 \\ 0 \\ 2.952 \end{bmatrix} = 2.976 \begin{bmatrix} 1 \\ 0 \\ 0.992 \end{bmatrix} = \lambda^{(5)} x^{(5)}$$

$$AX^{(5)}: \begin{bmatrix} 2 & 0 & 1 \\ 0 & 2 & 0 \\ 1 & 0 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 0.992 \end{bmatrix} = \begin{bmatrix} 2.992 \\ 0 \\ 2.984 \end{bmatrix} = 2.992 \begin{bmatrix} 1 \\ 0 \\ 0.997 \end{bmatrix} = \lambda^{(6)} x^{(6)}$$

After 6 iterations, the appropriate eigen value is $\lambda = 2.992$ and the corresponding eigen vector is $x = \begin{bmatrix} 1 \\ 0 \\ 0.997 \end{bmatrix}$

10)a) Solve the following system of equations by gauss seidel method
 $10x + y + z = 12$, $x + 10y + z = 12$, $x + y + 10z = 12$

→ The given system of equation are diagonally dominant.
 Gauss - sieidel method is given by -

$$x = \frac{12 - y - z}{10} \quad \text{--- (1)} \quad y = \frac{12 - x - z}{10} \quad \text{--- (2)} \quad z = \frac{12 - x - y}{10} \quad \text{--- (3)}$$

Let the initial approximation be $(x^{(0)}, y^{(0)}, z^{(0)}) = (0, 0, 0)$

Ist iteration: $x^{(1)} = \frac{12 - 0 - 0}{10} = 1.2$

$$y^{(1)} = \frac{12 - 1.2 - 0}{10} = 1.08$$

$$z^{(1)} = \frac{12 - 1.2 - 1.08}{10} = 0.972$$

$$\therefore (x^{(1)}, y^{(1)}, z^{(1)}) = (1.2, 1.08, 0.972)$$

IInd iteration: $x^{(2)} = \frac{12 - 1.08 - 0.972}{10} = 0.9948$

$$y^{(2)} = \frac{12 - 0.9948 - 0.972}{10} = 1.0033$$

$$z^{(2)} = \frac{12 - 0.9948 - 1.0033}{10} = 1.0001$$

$$\therefore (x^{(2)}, y^{(2)}, z^{(2)}) = (0.9948, 1.0033, 1.0001)$$

$$\text{III}^{\text{rd}} \text{ iteration: } x^{(3)} = \frac{12 - 1.0033 - 1.0001}{10} = 0.9996$$

$$y^{(3)} = \frac{12 - 0.9996 - 1.0001}{10} = 1.0000$$

$$z^{(3)} = \frac{12 - 0.9996 - 1.0000}{10} = 1.0000$$

$$\therefore (x^{(3)}, y^{(3)}, z^{(3)}) = (0.9996, 1.0000, 1.0000)$$

10) b) For what values of a and b the system of equation :

$$x + y + z = 6 ; x + 2y + 3z = 10 ; x + 2y + az = b \text{ has -}$$

(i) no solution (ii) a unique solution (iii) infinite number of solution

→ Consider the augmented matrix

$$[A:B] = \begin{bmatrix} 1 & 1 & 1 & : & 6 \\ 1 & 2 & 3 & : & 10 \\ 1 & 2 & a & : & b \end{bmatrix}$$

$$R_2 \rightarrow R_2 - R_1 ; R_3 \rightarrow R_3 - R_1$$

$$[A:B] = \begin{bmatrix} 1 & 1 & 1 & : & 6 \\ 0 & 1 & 2 & : & 4 \\ 0 & 1 & a-1 & : & b-6 \end{bmatrix}$$

$$R_3 \rightarrow R_3 - R_2$$

$$[A:B] = \begin{bmatrix} 1 & 1 & 1 & : & 6 \\ 0 & 1 & 2 & : & 4 \\ 0 & 0 & a-3 & : & b-10 \end{bmatrix}$$

(i) NO solution:
we must have $\rho(A) \neq \rho[A:B]$

If $a=3$, then $\rho(A)=2$

If $b \neq 10$, then $\rho[A:B]=3$

$\therefore$ system of equations have no solution if $a=3$, $b \neq 10$

(ii) Unique solution:

we must have $\rho(A)=\rho[A:B]=r=n=3$

If $a \neq 3$, then $\rho(A)=3$

Irrespective of the value of μ , $\rho[A:B]=3$

$\therefore$ system has unique solution if $a \neq 3$ and for any b

(iii) infinite solution:

we must have $r < n$

Since $n=3$, we must have $r=2$

$\rho(A)=2$ if $a=3$

$\rho[A:B]=2$ if $b=10$

$\therefore$ Thus system will have infinite solution if $a=3$ and $b=10$.

10c) solve the system of equations by gauss elimination method
 $x+y+z=9$, $x-2y+3z=8$, $2x+y-z=3$

$\rightarrow$ consider the augmented matrix

$$[A:B] = \left[\begin{array}{ccc|c} 1 & 1 & 1 & 9 \\ 1 & -2 & 3 & 8 \\ 2 & 1 & -1 & 3 \end{array} \right]$$

$$R_2 \rightarrow R_2 - R_1; \quad R_3 \rightarrow R_3 - 2R_1$$

$$[A:B] = \left[\begin{array}{ccc|c} 1 & 1 & 1 & 9 \\ 0 & -3 & 2 & -1 \\ 0 & -1 & -3 & -15 \end{array} \right]$$

$$R_3 \rightarrow 3R_3 - R_2$$

$$[A:B] \sim \begin{bmatrix} 1 & 1 & 1 & : & 9 \\ 0 & -3 & 2 & : & -1 \\ 0 & 0 & -11 & : & -44 \end{bmatrix}$$

This is in upper triangular matrix

$$x + y + z = 9$$

$$-3y + 2z = -1$$

$$-11z = -44$$

$$\Rightarrow \boxed{z = 4}$$

$$\Rightarrow -3y + 2(4) = -1$$

$$-3y = -9$$

$$\boxed{y = 3}$$

$$\Rightarrow x + y + z = 9$$

$$x + 3 + 4 = 9$$

$$\boxed{x = 2}$$

$\therefore$ solution is $x = 2$, $y = 3$, $z = 4$.